

## Homework #5, PHY 674, 04 October 1995

Let  $G$  be a group of order  $n$ . The regular character is given by

$$\chi_{\text{reg}}(g) = \begin{cases} 0 & \text{if } g \in G, g \neq e \in G \text{ and} \\ n & \text{if } g = e \in G. \end{cases} \quad (21.1)$$

Calculate the regular character for the equilateral triangle group. Now calculate

$$\sum_{i=1}^s d_i \chi_i(g) \quad (21.2)$$

for all  $g \in G$  and compare. Surprised? ( $s$  is the number of classes and  $d_i$  the dimension of the  $i$ -th irreducible representation.) See the script for details (4 points).

Setup the regular representation of the equilateral triangle group. That is to say: For each element  $g$  in the group write down the  $6 \times 6$  matrix that represents  $g$ . Here's how to do it (in case you don't like the definition in the script): Take your multiplication table for  $C_{3v}$  and rearrange it in such a way that each element faces its inverse, that is the all diagonal elements are the neutral element. Now, the matrix representing the group element  $g$  is obtained in this way: If the entry in the multiplication table is  $g$ , write down 1 in the corresponding place in the matrix, otherwise write down 0. Now that you have all the matrices of the representation, find the character of the regular representation. Does it agree with what you calculated in the previous problem? Is the character really a class function, i.e., constant within classes? I will spare you the task of finding a  $6 \times 6$  matrix that reduces this representation to block-diagonal form showing how the regular representation reduces into irreducible representation.

Let  $R$  be a rotation by  $90^\circ$  about the  $x$ -axis. How do the following functions transform under this rotation? (In other words, given  $R$  and  $f$  calculate  $PRf$  for the following functions.)

$$1) f(\vec{r}) = x\phi(r),$$

$$2) f(\vec{r}) = y\phi(r),$$

$$3) f(\vec{r}) = z\phi(r),$$

$$\text{where } r = \sqrt{x^2 + y^2 + z^2}.$$

Now that

$$(T_{m\vec{v}} - 1) H(\vec{r}, \vec{p}, t) = [H, \vec{G}] \cdot \vec{v} \quad (24.3)$$

for all functions  $H$  and all (sufficiently small) vectors  $\vec{v} = \dot{\vec{r}}$ , where  $\vec{G}$  is given by

$$\vec{G} = m\vec{r} - t\vec{p} \quad (24.4)$$

and  $T_{m\vec{v}}$  is the operator acting on  $H$  like

$$T_{m\vec{v}} H(\vec{r}, \vec{p}, t) = H(\vec{r} - t\vec{v}, \vec{p} - m\vec{v}, t). \quad (24.5)$$

Do NOT assume that  $\vec{p} = m\vec{v} = m\dot{\vec{r}}$  for this problem.

Problems are worth 4 points each.